LOK JAGRUTI UNIVERSITY (LJU)

INSTITUTE OF ENGINEERING AND TECHNOLOGY

Department of Mechanical Engineering (710)

Bachelor of Engineering (B.E.) – Semester – III

Course Code:	urse Code: 017103392		Teaching Scheme				
Course Name:	urse Kinematics of Machines Lectu ial			Pract ical (P)	Cre dit	Tota l Hou rs	
Category of Course:	Professional Core Course (PCC)						
Prerequisite Course:	erequisite Mathematics 1 (017101191), Engineering Graphics 1 (017102191), Engineering Mechanics (017102291), Strength		4	1	2	6	50

	Syllabus					
Unit No.	Торіс	Prerequisite Topic	Successive Topic	Teac hing Hour s		
	Introduction of Mechanisms and M	I achines	_			
01	 1.1 Concepts of kinematics and dynamics, mechanisms and machines, Kinematic link and its types (Resistance, Flexible and Fluid link), Kinematic Joint and its types (Binary, ternary and Quaternary Joint) 1.2 Kinematic Pair and its Classification 	Kinematics (017102291-Unit- 10.1)		- 6		
01	(Higher and Lower Pair, Turning pair, Rolling pair, Sliding pair, Screw pair, Spherical pair, Open and closed pair), kinematic chains			(12%)		
	1.3 Degrees of freedom for 2-D, mobility- Kutzbach and Grubler's criterion, Grashof's criterion					
	Inversion of Mechanisms					
	2.1 Kinematic inversion, inversion of four bar chain(Double Crank Mechanism, Crank-Rocker Mechanism, Rocker- Rocker Mechanism)			6		
02	2.2 Inversion of Single slider crank mechanisms (Reciprocating Engine, Rotary Engine, Whitworth QRRM, Oscillating Cylinder mechanism, Crank and Slotted bar Mechanism, Hand pump mechanism)			6 (12%)		

	2.3 Inversion of double slider crank				
	mechanisms (Elliptical Trammel				
	mechanism, Scotch yoke mechanism,				
	Oldham's Coupling)				
	Kinematics: Velocity Analysis				
	3.1 Introduction, Space and Body				
	Centrodes, Determine the Velocity of a				
	Point on a link, Instantaneous centre of	Velocity (017102291-			
	velocity, properties of Instantaneous	Unit-10.1)			
	centre, Number of Instantaneous centres				
	in Mechanism,			6	
03	3.2 Types of Instantaneous centres (Fixed, Permanent and Neither fixed nor			(12%)	
	permanent), Location of Instantaneous			(12/0)	
	centres, Method of Locating				
	Instantaneous centres in a Mechanism				
	3.3 Kennedy theorem, angular velocity	Instantaneous method			
	ratio theorem	(017103392-Unit-03)			
	3.4 Rubbing Velocity at a Pin joint,				
	Relative velocity analysis				
	Kinematics: Acceleration Analysis				
	4.1 Definition of acceleration, angular	Acceleration			
	acceleration, a general case of	(017102291-Unit-			
	acceleration, radial and transverse	10.1)			
04	components of acceleration	,		6	
04	4.2 Examples of acceleration analysis, acceleration diagrams	Velocity diagram (017103392-Unit-03)		(12%)	
		Velocity diagram			
	4.3 Klein's construction analysis,	(017103392-Unit-03),			
	corioli's component of acceleration	Acceleration diagram			
		(017103392-Unit-04)			
	Toothed Gears				
	5.1 Introduction, classification of gears				
	(spur gear, helical gear, double helical,				
	bevel gear, metre gear, spiral gear, rack				
	and pinion gear, worm and worm wheel				
	gear, internal and external gear) 5.2 Gear terminology (Pitch, Pitch Point,			_	
	Pitch circle, Pitch circle diameter, Pitch				
	point, Pressure angle, Addendum,				
	Dedendum, Addendum radius,			6	
05	Dedendum radius, Clearance circle,	Velocity (017102291-	Gears (017073301-	6 (12%)	
	Circular pitch, Module, Diametral pitch,	Unit-10.1)	Unit-10.3)	(12/0)	
	Gear ratio, Base circle, Backlash, Top				
	and Bottom Land, Face, Flank, Path of				
	contact, Arc of contact), law of gearing, velocity of sliding				
	5.3 Forms of teeth, cycloidal profile teeth,	Cycloidal and		-	
	involute profile teeth, comparison of	involute profile			
	cycloidal and involute tooth forms	(017102291-Unit-6.1)			
	5.4 Path of contact, arc of contact,			1	
	Contact ratio				

	5.5 Concept of interference in involute				
	gears and its avoiding methods (modified tooth profile, modified in addendum and dedendum, Centre distance variation), minimum number of teeth on gear and pinion, undercutting	Path of contact (017103392-Unit-05)			
	Gear Trains				
06	6.1 Introduction of simple gear train, compound gear train, reverted gear train and epicyclic gear train (Derive Velocity ratio of each gear train)	Law of gearing (017103392-Unit-05)		5 (10%)	
	6.2 Analysis of epicyclic gear trains, Numericals based on (simple gear train, compound gear train, reverted gear train and epicyclic gear train)	Law of gearing (017103392-Unit-05)			
	Flywheels- Turning Moment Diagr	am			
	7.1 Introduction-significance of flywheel	Energy (017102291- Unit-10.2)			
07	7.2 Turning moment and crank effort diagrams for reciprocating machines (single cylinder 4 stroke IC engine, multi cylinder engine)	Torque (017102291- Unit-3.1)		2.5 (5%)	
	7.3 Coefficient of fluctuation of speed and energy, limiting velocity of flywheel, energy stored in flywheel	Energy and moment of inertia (017102291-Unit- 10.2,9.1)			
	Flywheels				
	8.1 Dimensions of flywheel rim (width and diameter of flywheel)	Stress and types of stress, Strain and types of strain (017103391-Unit-1.2)			
08	8.2 Flywheel in punching press	Stress and types of stress, Strain and types of strain (017103391-Unit- 1.2), Energy (017102291-Unit- 10.2)		2.5 (5%)	
	Cam				
	9.1 Introduction of cam and followers and their uses.				
09	9.2 Working and Types of Cam (Radial cam, Wedge Cam, Cylindrical Cam), Working and Types of Follower (knife edge, roller, flat face, mashroom, globoidal(convex-concave), spherical followers), Terminology (Base circle, trace point, prime circle, pitch point, Pressure angle, Pitch circle, angle of assent, angle of decent, Dwell)			4 (8%)	
	9.3 Displacement diagrams of follower	Basic differentiation			

	and retardation, simple harmonic motion, cycloidal motion)		
	Cam Profile		
10	10.1 Determine of basic dimensions and Layout of cam profiles using graphical methods	· · · · · · · · · · · · · · · · · · ·	 6 (12%)

Sr No.	Practical Title	Link to Theory Syllabus
1	To demonstrate of Types of link pair and motion.	Unit-1
2	To illustrate and the detailed analysis of the four-bar chain mechanism.	Unit-2
3	To demonstrate and analysis of single slider chain mechanism.	Unit-2
4	To exhibit and detailing of double slider mechanism.	Unit-2
5	To understand the working of simple gear & gear train used in Mechanical components.	Unit-6
6	To determine the nature and relationship of the parts of compound gear train in working condition.	Unit-6
7	To understand epicyclic gear train working by examining.	Unit-6
8	To get explicit knowledge of flywheel and its design in engineering.	Unit-7
9	To demonstrate and comprehend every term and terminology of cam and follower.	Unit-9

Proposed Theory + Practical Evaluation Scheme by Academicians (% Weightage Category Wise and it's Marks Distribution) (New version for KOM)

L:	4	T:	1	P:	2	
Note: In Theory Group, Total 4 Test (T1+T2+T3+T4) will be conducted for each subject. Each Test will be of 25 Marks. Each Test Syllabus Weightage: Range should be 20% - 30%						
Group (Theory or Practical)	Group (Theory or Practical) Credit	Total Subject Credit	Category	% Weightage	Marks Weightage	
Theory			MCQ	38%	45	
Theory	5		Theory Descriptive	3%	4	
Theory			Formulas and Derivation	10%	12	
Theory			Numerical	33%	39	
Expected Theory %	84%	6	Calculated Theory %	84%	100	
Practical			Individual Project	10%	60	
Practical		In	Group Project	0%	0	
Practical	1		Internal Practical Evaluation (IPE)	0%	0	
Practical			Viva	6%	40	
Practical			Seminar	0%	0	
Expected Practical %	16%		Calculated Practical %	16%	100	
Overall %	100%			100%	200	

Cour	Course Outcome					
Upon	Upon completion of the course students will be able to					
1	demonstrate design thinking capability and identify functional characteristics of various machine elements. Also, the ability to analyze motion of mechanisms.					
2	Determine position, velocity and acceleration of linkages in mechanism at any instant.					
3	Understand basics of gear and importance of gear train and Ability to construct turning moment diagram and flywheel design.					
4	Application of Fly-Wheel and analyze cam motion profiles and follower mechanism.					
Sugg	ested Reference Books					
1	Theory of Machines by S.S.Rattan, Tata McGraw-Hill Publishing Co. Ltd. New Delhi					
2	Theory of Machines and Mechanisms by Shigley, J.E and Uicker, J.J, Oxford University Press					
3	Mechanisms and Machine theory by Rao J.S. and Dukkipati R.V, Wiley Eastern Ltd.					
4	Theory of Machines by Singh Sadhu, Pearson Education					
5	Kinematics and Dynamics of Machinery by Wilson: 3rd Edition, Pearson Education					
6	Mechanism and Machine Theory by A G Ambekar, PHI.					
7	Kinematics, Dynamics and Design of Machinery by Kenneth J Waldron, Gary L Kinzel, Wiley					
8	Kinematics and Dynamics of Machinery by R L Norton, McGraw-Hill					

List of Open Source Software/Learning website

http://nptel.ac.in

1

2	www.learnerstv.com
3	http://kmoddl.library.cornell.edu
4	https://www.coursera.org
5	https://www.edx.org
6	https://in.linkedin.com
7	https://www.skill-lync.com

	Practical Project/Hands on Project				
Sr. No.	Project List		Linked with Unit		
1	Make a model based on application of fluid link in mechanism. (Example Hydraulic Crane).		Unit 01		
2	Select any model based on 2D planner mechanism and calculate DOF using python program. (Example oldham's coupling).	Flange (Link 1) Detving shaft Uink 4) (Link 3) frame (Link 2) (Link 2) (Link 3) (Link 4) (Link 3) (Link 4) (Link 4) (Lin	Unit 01		
3	To prepare model for analysis of Grashof's law and also prepare python program for the same. (Four bar chain mechanism)	Moving Pivot Fixed Pivot Fixed Pivot	Unit 01		
4	Make a project on any one application of four bar chain mechanism. (Example Watt's indicator Mechanism).	Watt's indicator mechanism	Unit 02		
5	Demonstrate the application of Single Slider chain mechanism by using model. (Example Quick return motion mechanism).	Link 2: Crank Link 2: Crank Link 3: Fin eliding in the elot i	Unit 02		

6	Prepare a model and explain application of Double Slider chain mechanism. (Example Oldham's coupling).	Flange (Link 1) Driving shaft A (Link 2) (Link 3) (Link 4) (Link 4) (Unit 02
7	Make a project of Gear drive mechanism. Determine minimum number of teeth required to avoid interference on gear and pinion by using python.	Spur Gear Rack and Pinion	Unit 05
8	Demonstrate on any one gear train application by using python. (Example Epicyclic gear train).		Unit 06
9	Analysis of velocity ratio of gear train using python and also give the demonstration by preparing a model of respective gear train.	Compound Spur Gear Gear Train	Unit 06
10	Demonstrate any one application of flywheel with model. (Example sewing machine).	Wat is a Plywheet? Concentration of the state of the sta	Unit 08
11	To prepare the model of any application of Cam and follower. Determine maximum and minimum velocity and acceleration during rise and return of follower using python program.	Spring Wedge shape cam	Unit 09